

HEB



JOPD

Journal of Prosthodontics Dentistry
An Official Publication of Bureau for Health & Education Status Upliftment
 (Constitutionally Entitled as Health-Education, Bureau)

Robotics in Implantology – Boon Or Bane

¹Thabu Rani.C¹, Dr. Dhanalakshmi P² MDS, Dr. Bindu vaithilingam ³MDS, & Dr Ashn S ⁴MDS

¹CRI Vinayaka Mission Sankarachariyar Dental College, Salem

²Assistant Professor, De Professor partment of Prosthodontics and Crown & Bridge, Vinayaka Mission's Sankarachariyar Dental College, Vinayaka Mission's Research Foundation (Deemed to be University), Ariyanoor, Tamil Nadu, India 636 308

³Professor, Department of Prosthodontics and Crown & Bridge, Vinayaka Mission's Sankarachariyar Dental College, Vinayaka Mission's Research Foundation (Deemed to be University), Ariyanoor, Tamil Nadu, India 636 308

⁴Assistant Professor, Department of Prosthodontics and Crown & Bridge, Vinayaka Mission's Sankarachariyar Dental College, Vinayaka Mission's Research Foundation (Deemed to be University), Ariyanoor, Tamil Nadu, India 636 308

Correspondence:

Thabu Rani C, CRI, Vinayaka Mission Sankarachariyar Dental College, Salem

Email Id: serviceheb@gmail.com

Abstract:

Robotic surgery is already a reality not just science fiction. Currently, preoperative medical imaging and the doctor's clinical experience are the two main sources of support for dental implant surgery. Nonetheless, there are a few issues with dental implant surgery, including confined spaces, obstructions to vision, incorrect placement. Consequently, a robot for dental implants system (DIRS) with optical navigation guidance is created wherein an x-shaped tool and an irregular pentagonal tracer are constructed for needle tip positioning strategy and spatial registration, respectively. The coordinate framework through system calibration, spatial registration, and needle tip positioning method, each DIRS unit is brought together. Prior to surgery, the navigation software uses the computed tomography (CT) pictures to calculate the surgical course. In the process, the auxiliary positioning method and the automatic positioning method can be employed to obtain precise location and help medical professionals finish the procedure.

Key word: Robotic guided implantology, Fully autonomous robotic implantology, Robotic workflow, Yomi system

Access this Article Online	Quick Response Code: 
Website: http://heb-nic.in/jopd	
Received on 22/11/2023	
Accepted on 07/12/2023 © HEB All rights reserved	

